

Neural Networks and HPC synergy

Raphael Cóbe Rogério Iope Silvio Stanzanni Jefferson Fialho {rmcobe,rogerio,silvio,jfialho}@ncc.unesp.br

- an algorithm that is able to learn from data;
- what do we mean by learning?

"A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E."

- Tom Mitchel

- allows us to tackle tasks that are too difficult to solve with fixed programs
- process examples;
- tasks:
 - classification, clustering, regression, translation, ...

- the experience:
 - unsupervised
 - inference from data structure
 - supervised
 - learn by examples;

- The more data, the best!
 - Overfitting and Underfitting;
- Common solutions:
 - linear regression, k-means, logistic regression, support vector machines, etc...

Neural Networks

- Receive input from other units and decides whether or not to fire.
- ~ 86 billion neurons in the human nervous system
 - connected with approximately 10^14 -10^15 synapses

- input signals from its dendrites;
- output signals along its (single) axon;
- interact multiplicatively (e.g. w₀x₀) with the dendrites of the other neuron based on the synaptic strength at that synapse (e.g. w₀);
- learn synapses strengths;

- control the influence from one neuron on another:
 - excitatory when weight is positive; or
 - inhibitory when weight is negative;
- nucleus is responsible for summing the incoming signals;
 - if the sum is above some threshold, then fire!





Images from Stanford CS231

Neural Networks

Function approximation machines;

• $y = f^*(x)$

• maps x input to a y category

• y = f(x; w)

ullet learn the value of the w parameters

Neural Networks

- Input, Output, and Hidden layers;
- Hidden as in "not defined by the output";
- Approximate y = f(x; w) to $y = f^*(x)$ (training)

Neural Networks Hidden Layers

- Seen as vector-valued, i.e. a vector is received as input and a new vector is produced as output;
 - (vector-to-vector function);
- Units that work in parallel.
 - (vector-to-scalar function);

Neural Networks

- Activation Function:
 - Describes whether or not the neuron fires, i.e., if it forwards its value for the next neuron layer;
- multiply the input by its weights, add the bias and apply the non-linearity;
- Sigmoid, Hyperbolic Tangent, Rectified Linear Unit;

Neural Networks

class Neuron(object):
 def forward(inputs):
 """ assume inputs and weights are 1-D
 numpy arrays and bias is a number """

cell_body_sum = np.sum(inputs * self.weights) + self.bias

ReLU activation function
firing_rate = np.maximum(cell_body_sum, 0, cell_body_sum)
return firing_rate

- In 1958, Frank Rosenblatt proposed an algorithm for training the perceptron.
- Simplest form of Neural Network;
- One unique neuron;
- Adjustable Synaptic weights;
- Simple activation function;

 Classifies inputs into two classes, with neuron output of either -1 or 1;



- \bullet Where ϕ is the activation function and J_1 the number of inputs
- Always converge on linearly separable classes;

$$net = \sum_{i=1}^{J_1} w_i x_i - \theta = w^T x - \theta$$
$$y = \phi(net)$$

- Training Procedure:
- η is the learning rate;
- finds a linear function that separates the classes;

$$e_p = y_p - \hat{y}_p$$

 $w_i(t+1) = w_i(t) + \overline{\eta x_{p,i} e_i}$

- Can't do:
 - separate non linear classes;
 - XOR function:



Feedforward Networks

 typically represented by composing many different functions:

$$f(x) = f^{(3)}(f^{(2)}(f^{(1)}(x)))$$

 the depth of the network - the deep in deep learning! (-;

Feedforward Networks

- Information flows from x, through f computations and finally to y
- No feedback!



Feedforward Networks Hidden Layers

- Train using a back-propagation algorithm from 1969;
 - fixes the weights in an output-to-input direction;
- each level has plays a specific role in the classification;
- detect the features in the input patterns;

Feedforward Networks How it works

• The output of a Feedforward Network:

$$\hat{y}_p = o_p^{(M)}, \ o_p^1 = x_p$$

• The output of the m layer:

$$net_p^{(m)} = [W^{(m-1)}]^T o_p^{(m-1)} + \theta^{(m)}$$
$$o_p^{(m)} = \phi^{(m)} (net_p^{(m)})$$

- suppose we want to learn the behavior of the binary XOR operator:
- the input will be a pair of signals with value either 0 or 1.
- The output should be classified also into 0 or 1;

• The dataset:

- 1 1 0

The network:



- The architecture: 2 layer network (one hidden and one for output)
- Rectified linear Unit as activation function, i.e. $\phi(net_p^{(1)}) = max(net_p^{(1)},0)$
- Why not a linear function?

• The full expanded solution:

$$y = W_2^T(max(0, W_1^T x + \theta_1)) + \theta_2$$

• Running the example:

$$W_{1} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \qquad \theta_{1} = \begin{bmatrix} 0 \\ -1 \end{bmatrix} \qquad X = \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$
$$W_{2} = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \qquad \theta_{2} = 0$$

• Running the example:

$$net^{(1)} = W_1 X + \theta_1 = \begin{bmatrix} 0 & -1 \\ 1 & 0 \\ 1 & 0 \\ 2 & 1 \end{bmatrix}$$

$$\phi(net^{(1)}) = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 2 & 1 \end{bmatrix}$$

• Running the example:

$$o^{(2)} = net^{(2)} = W_2 o^{(1)} + \theta_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

- most popular learning rule for performing supervised learning tasks;
- No only used in Feedforward learning;
- propagates backward the error between the signal and the network output through the network;
- continuous, nonlinear, differentiable activation function
 - sigmoid functions, hyperbolic tangent;

 Indexes i,j,k refer to neurons in input, hidden and output layers;



 Input signals flow from left to right and error signals from right to left;



 $\bullet \; w_{ij} \, {\rm represents}$ the weight that connects the input neuron i and the neuron in the hidden layer j

• w_{jk} the weight between the neuron j in the hidden layer and the neuron k in the output layer



• objective function for optimization is defined as the MSE between the \hat{y}_p and the desired output y_p :

 $e_{p,k} = \hat{y}_{p,k} - y_{p,k}$

- first step is to correct the weight between j and k by minimizing the error;
 - error gradient, learning rate;

$$w_{p+1,jk} = w_{p,jk} + \Delta w_{p,jk}$$

$$\Delta w_{p,jk} = \alpha y_{p,j} \delta(\hat{y}_{p,k})$$

$$\Delta w_{p,ij} = \alpha x_{p,i} \delta(\hat{y}_{p,j})$$

• It gets uglier!

Neural Networks Gets better

- Programming APIs:
 - PyTorch;
 - Theano;

•••

• TensorFlow;

Neural Networks Gets better

```
def forwardprop(X, w_1, w_2):
    """ Forward-propagation """
    h = T.nnet.sigmoid(T.dot(X, w_1)) # The \sigma function
    yhat = T.nnet.softmax(T.dot(h, w_2)) # The \varphi function
    return yhat
```

```
def backprop(cost, params, lr=0.01):
    """ Back-propagation """
    grads = T.grad(cost=cost, wrt=params)
    updates = []
    for p, g in zip(params, grads):
        updates.append([p, p - g * lr])
    return updates
```

Questions?